A Generic Deskolemization Strategy

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First-Order Logic for Proof Assistants

- sequent calculi or natural deduction
- Here Sequent Calculus GS3 (left-sided)

$$\frac{\Gamma, P, Q}{\Gamma, P \land Q} \land \frac{\Gamma, P}{\Gamma, \neg \neg P} \neg \neg \frac{\Gamma, \neg P, \neg Q}{\Gamma, \neg (P \lor Q)} \neg \lor \frac{\Gamma, P, \neg Q}{\Gamma, \neg (P \Rightarrow Q)} \neg \Rightarrow \\
\frac{\Gamma, P}{\Gamma, P \land Q} \land \frac{\Gamma, P}{\Gamma, \neg \neg P} \neg \neg \frac{\Gamma, \neg P, \neg Q}{\Gamma, \neg (P \lor Q)} \neg \lor \frac{\Gamma, \neg P, \neg Q}{\Gamma, \neg (P \Rightarrow Q)} \neg \Rightarrow \\
\frac{\Gamma, P}{\Gamma, P \lor Q} \lor \frac{\Gamma, \neg P, \neg Q}{\Gamma, P \Rightarrow Q} \Rightarrow \frac{\Gamma, \neg P, \neg Q}{\Gamma, \neg (P \land Q)} \neg \land \\
\frac{\Gamma, \forall x. P, P[x \mapsto t]}{\Gamma, \forall x. P} \forall \qquad \frac{\Gamma, \neg \exists x. P, \neg P[x \mapsto t]}{\Gamma, \neg \exists x. P} \neg \exists \\
\frac{\Gamma, \exists x. P, P[x \mapsto c^*]}{\Gamma, \neg \forall x. P} \exists \qquad \frac{\Gamma, \neg \forall x. P, \neg P[x \mapsto c^*]}{\Gamma, \neg \forall x. P} \neg \forall$$

First-Order Logic for Automated Theorem Proving

Refutation methods, rather than direct proofs:

- tableaux, here (Goéland, concurrent & parallel ATP)
- postpone instantiation of universal variables
 - ★ leave Free Variables (aka "Meta") instead
 - ★ instantiate at closing time
 - ★ freshness of existential constants c* under threat
 - ★ register the variables the constant depends on
 - * Skolem symbol, Skolem term
- ATPs need proof certificates

Our Contribution

Translation from free-variable tableaux to sequent calculus.

Free-Variable Tableaux Calculus

closure rules:

$$\frac{\bot}{\odot} \odot_{\bot} \qquad \frac{\neg \top}{\odot} \odot_{\neg \top} \qquad \frac{P, \neg Q}{\sigma} \odot_{\sigma}, \sigma(P) = \sigma(Q)$$

• α rules (non-branching connectives):

$$\frac{\neg \neg P}{P} \alpha_{\neg \neg} \qquad \frac{P \wedge Q}{P, Q} \alpha_{\wedge} \qquad \frac{\neg (P \vee Q)}{\neg P, \neg Q} \alpha_{\neg \vee} \qquad \frac{\neg (P \Rightarrow Q)}{P, \neg Q} \alpha_{\neg \Rightarrow}$$

• β rules (branching connectives):

$$\frac{P \vee Q}{P \quad Q} \beta_{\vee} \qquad \frac{P \Rightarrow Q}{\neg P \quad Q} \beta_{\Rightarrow} \qquad \frac{\neg (P \wedge Q)}{\neg P \quad \neg Q} \beta_{\neg \wedge}$$

• γ rules (universal quantifiers):

$$\frac{\neg \exists x. P}{P[x \mapsto X]} \gamma_{\forall} \qquad \frac{\neg \exists x. P}{\neg P[x \mapsto X]} \gamma_{\neg \exists}$$

• δ rules (existential quantifiers):

$$\frac{\exists x. P}{P[x \mapsto f(X_1, \dots, X_n)]} \delta_{\exists} \qquad \frac{\neg \forall x. P}{\neg P[x \mapsto f(X_1, \dots, X_n)]} \delta_{\neg \forall}$$

Example Tableau Proof: Drinker's Principle

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg\exists}} \gamma_{\neg\exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{\neg(D(X), \neg(\forall y \ D(y)))} \delta_{\neg\forall}^{+}$$

$$\frac{\neg D(c)}{\{X \mapsto c\}} \odot_{\sigma}$$

Tableau Proof

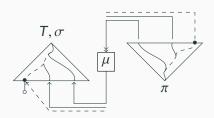
Proof tree and a uniform substitution σ that closes all the branches at once.

From Tableaux to Sequent Calculus

- usual induction : impossible (why : in a minute)
- instead : grow the sequent proof from the root
- needs discipline : maintain a mapping

Mapping

a function μ that associates to each leave of a sequent proof tree, an (internal) node of the tableau proof.



the node that a leaves maps to is "the next rule to be incorporated".

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists} \gamma_{\neg \exists} \\ \frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{D(X), \neg(\forall y \ D(y))} \delta_{\neg \forall}^{+} \\ \frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{\neg(D(X), \neg(\forall y \ D(y)))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y D(y))}{D(X), \neg(\forall y D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x.\ D(x) \Rightarrow \forall y\ D(y)), \neg(D(c) \Rightarrow \forall y\ D(y)) \vdash}{\neg(\exists x.\ D(x) \Rightarrow \forall y\ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{\neg(D(X), \neg(\forall y \ D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x.\ D(x) \Rightarrow \forall y\ D(y)), \neg(D(c) \Rightarrow \forall y\ D(y)) \vdash}{\neg(\exists x.\ D(x) \Rightarrow \forall y\ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y D(y))}{D(X), \neg(\forall y D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$
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$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X), \neg(\forall y \ D(y))}{\neg(\partial)} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$
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$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{\neg(X), \neg(\forall y \ D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg(C)}{\sigma = \{X \mapsto C\}} \odot_{\sigma}$$

Let the fun begin!

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \ \neg(D(c) \Rightarrow \forall y \ D(y)), \ D(c), \ \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \ \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \ \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{\neg(X), \neg(\forall y \ D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash} \neg \Rightarrow} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$
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$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y D(y))}{\neg(D(X), \neg(\forall y D(y)))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists} \\ \frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{D(X), \neg(\forall y \ D(y))} \delta_{\neg \forall}^{+} \\ \frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \xrightarrow{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \xrightarrow{\neg_{\exists}}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \xrightarrow{\neg_{\exists}}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}$$

$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y D(y))}{D(X), \neg(\forall y D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

Replay first, to grow back the missing formulas

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg D(c) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash} \neg_{\forall}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$
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$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg\exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y D(y))}{D(X), \neg(\forall y D(y))} \delta_{\neg\forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg D(c) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash} \neg_{\forall}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg_{\exists}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}$$

$$\frac{\neg (\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg (D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists}$$

$$\frac{\neg (D(X) \Rightarrow \forall y \ D(y))}{D(X), \neg (\forall y \ D(y))} \delta_{\neg \forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg D(c) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash} \neg \forall \qquad \forall x \ 2$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(x) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg (\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg (D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists} \\ \frac{\neg (D(X) \Rightarrow \forall y \ D(y))}{D(X), \neg (\forall y \ D(y))} \delta_{\neg \forall}^{+} \\ \frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg D(c) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg(D(c) \vdash} \neg \exists}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash}
\nabla(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}
\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y$$

$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg\exists}$$

$$\frac{\neg(D(X) \Rightarrow \forall y D(y))}{D(X), \neg(\forall y D(y))} \delta_{\neg\forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg(D(c) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg(D(c) \vdash} \neg \forall} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(x) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(x) \Rightarrow \forall y \ D(y)) \vdash}{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)) \vdash} \neg \exists$$

$$\frac{\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y))}{\neg(D(X) \Rightarrow \forall y \ D(y))} \gamma_{\neg \exists} \\ \frac{\neg(D(X) \Rightarrow \forall y \ D(y))}{D(X), \neg(\forall y \ D(y))} \delta_{\neg \forall}^{+} \\ \frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), D(c), \neg(\forall y \ D(y)), \neg D(c) \vdash \\
\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg D(c) \vdash \\
\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)), \neg(D(c) \vdash \\
\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash \\
\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)), \neg(\forall y \ D(y)) \vdash \\
\neg(\exists x. \ D(x) \Rightarrow \forall y \ D(y)), \neg(D(c) \Rightarrow \forall y \ D(y)) \vdash \\
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\neg(\exists x.$$

$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y))}{\neg(D(X) \Rightarrow \forall y D(y))} \gamma_{\neg\exists}$$

$$\frac{\neg(D(X), \neg(\forall y D(y))}{\neg(D(x), \neg(\forall y D(y))} \delta_{\neg\forall}^{+}$$

$$\frac{\neg D(c)}{\sigma = \{X \mapsto c\}} \odot_{\sigma}$$

$$\frac{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)), D(c), \neg(\forall y D(y)), \neg D(c) \vdash}{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)), \neg(\forall y D(y)), \neg D(c) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(\forall y D(y)), \neg(D(c) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(\forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)), D(c), \neg(\forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow \forall y D(y)) \vdash} \xrightarrow{\neg(\exists x. D(x) \Rightarrow \forall y D(y)), \neg(D(c) \Rightarrow (D(c) \Rightarrow D(c) \Rightarrow$$

Key Steps

Consider a seq. cal. proof-tree π , and a mapping to a tableau T.

- Given a tableau non δ -rule to be incorporated : do it.
- If it is a δ -rule:
 - 1. weaken the formulas containing the offensive Skolem (\simeq fresh) term.
 - **2.** apply the δ -rule (no more offense here)
 - **3.** regenerate all the weakened formulas by replaying rules of π .
- note: the mapping is lost after weakening. We must regain it after step 3. This is hard.

Basic Notions

Context : tableau proof T with substitution σ .

Descendance

The descendance of F on a branch of T is the sequence of formulas originating from F.

Dependency

 $\forall x.A$ depends on $\exists y.D$ iff one of its direct descendant uses the Skolem term.

Dependency descendance

Sequence of descendants of a dependent F, that contain the Skolem term of interest and that appear on the node.

Consider the following tableau proof

$$\frac{\frac{\forall y.((P(y) \land \exists x. \neg P(x)) \lor F)}{(P(Y) \land \exists x. \neg P(x)) \lor F} \gamma_{\forall}}{(P(Y) \land \exists x. \neg P(x)) \lor F} \beta_{\lor}
\frac{P(Y) \land \exists x. \neg P(x)}{P(Y), \exists x. \neg P(x)} \delta_{\exists}
\vdots
\frac{\neg P(c)}{\{Y \mapsto c\}} \odot$$

 π : proof-tree (under construction) for the *F*-branch.

$$\frac{\psi, \cdots, P(c), \exists x. \neg P(x) \vdash}{\psi, \cdots, P(c) \land (\exists x. \neg P(x)) \vdash} \land \qquad \pi$$

$$\frac{\psi, \cdots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash}{\psi = \forall y. ((P(y) \land (\exists x. \neg P(x))) \lor F) \vdash} \forall$$

 π : proof-tree (under construction) for the F-branch.

Step 1: weaken* the offensive formulas (*c*-dependent descendants)

$$\frac{\psi, \exists x. \neg P(x) \vdash}{\psi, \cdots, P(c), \exists x. \neg P(x) \vdash} W \times 3$$

$$\frac{\psi, \cdots, P(c) \land (\exists x. \neg P(x)) \vdash}{\psi, \cdots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash} \pi$$

$$\frac{\psi, \cdots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash}{\psi = \forall y. ((P(y) \land (\exists x. \neg P(x))) \lor F) \vdash} \forall^*$$

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 π : proof-tree (under construction) for the *F*-branch.

Step 2 : ∃ rule and Skolem term/fresh symbol

$$\frac{\psi, \exists x. \neg P(x), \neg P(c) \vdash}{\psi, \exists x. \neg P(x) \vdash} \exists$$

$$\frac{\psi, \exists x. \neg P(x) \vdash}{\psi, \dots, P(c), \exists x. \neg P(x) \vdash} W \times 3$$

$$\frac{\psi, \dots, P(c) \land (\exists x. \neg P(x)) \vdash}{\psi, \dots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash} \checkmark^*$$

$$\frac{\psi, \dots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash}{\psi = \forall y. ((P(y) \land (\exists x. \neg P(x))) \lor F) \vdash} \checkmark^*$$

 π : proof-tree (under construction) for the *F*-branch.

Step 3: replay the gray* rules, grow back weakened formulas

$$\frac{\psi, \exists x. \neg P(x), \neg P(x) \land (\exists x. \neg P(x))) \lor F +}{\psi, \exists x. \neg P(x), \neg P(x) +} \exists \frac{\psi, \exists x. \neg P(x) \land \psi}{\psi, \dots, P(x), \exists x. \neg P(x) \land} W \times 3$$

$$\frac{\psi, \dots, P(x) \land (\exists x. \neg P(x)) \land}{\psi, \dots, P(x) \land (\exists x. \neg P(x)) \land} \wedge^* \qquad \pi$$

$$\frac{\psi, \dots, (P(x) \land (\exists x. \neg P(x))) \lor F \land}{\psi = \forall y. ((P(y) \land (\exists x. \neg P(x))) \lor F) \land} \vee^*$$

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 π : proof-tree (under construction) for the *F*-branch.

Step 3 : Beware of branching rules

$$\frac{\cdots, \neg P(c), \cdots, P(c) \land (\exists x. \neg P(x)) \vdash \pi}{\cdots, \neg P(c), \cdots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash} \lor \\
\frac{\psi, \exists x. \neg P(x), \neg P(c) \vdash}{\psi, \exists x. \neg P(x) \vdash} \exists \\
\frac{\psi, \exists x. \neg P(x) \vdash}{\psi, \cdots, P(c), \exists x. \neg P(x) \vdash} W \times 3 \\
\frac{\psi, \cdots, P(c) \land (\exists x. \neg P(x)) \vdash}{\psi, \cdots, P(c) \land (\exists x. \neg P(x))) \lor F \vdash} \lor^* \\
\frac{\psi, \cdots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash}{\psi = \forall y. ((P(y) \land (\exists x. \neg P(x))) \lor F) \vdash}$$

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 π : proof-tree (under construction) for the *F*-branch.

Step 3: replay the gray* rules, grow back weakened formulas

$$\frac{\cdots, \neg P(c), \cdots, P(c), \exists x. \neg P(x) \vdash}{\cdots, \neg P(c), \cdots, P(c) \land (\exists x. \neg P(x)) \vdash} \land \frac{\pi}{}$$

$$\frac{\cdots, \neg P(c), \cdots, (P(c) \land (\exists x. \neg P(x))) \lor F \vdash}{\psi, \exists x. \neg P(x) \vdash} \forall$$

$$\frac{\psi, \exists x. \neg P(x) \vdash}{\psi, \exists x. \neg P(x) \vdash} \exists$$

$$\frac{\psi, \cdots, P(c), \exists x. \neg P(x) \vdash}{\psi, \cdots, P(c), \exists x. \neg P(x)) \vdash} \forall^*$$

$$\frac{\psi, \cdots, P(c) \land (\exists x. \neg P(x)) \lor F \vdash}{\psi = \forall y. ((P(y) \land (\exists x. \neg P(x))) \lor F) \vdash} \forall^*$$
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 π : proof-tree (under construction) for the *F*-branch.

Then: keep going (maybe!)

The Crux of the Problem



An annoying chain of consequences:

- replay missing branching rule \Rightarrow duplicate π
- different sequent leaves mapped to the same tableau rule
- some leaves of π may be mapped to the \exists/δ -rule to incorporate
- incoporating a rule on one leaf ⇒ more hydra heads
- this happens (not on the example, though)
- does not look like we are making any progress
- ▶ takeaway: Step 3 (replay) is complex

Meet the Strategy Rules

Strategy Rule

When replaying the \vee , if a branch of π maps to the same δ -rule, additionally keep **relevant** formulas.

- we provide a list of conditions that strategy rules must satisfy
- we prove that those conditions ensure termination
- ► and we also prove

Proposition

It is ok to do so (will not break any other freshness condition in π).

- works for any skolemization that respects some requirements
- ► at least : outer, inner, pre-inner.

More Detail

- Skolem term ≈ constant, as soon as rules are in the correct order. So we get a real sequent calculus proof.
- Pain is mandatory: Skolemization leads to huge speed-up. Deskolemizing cannot avoid huge blow-up (at places).
- Ensuring progression: a strategy rule has to yield a smaller mapping at the end.

Benchmark

	Problems Proved	Avg. proof size	Avg. size increase	Max. size increase	Avg. time deskolem- ization (ms)	Avg. time translation Seq. Cal. → Coq (ms)
Goéland	261	6.9	0 %	_	72.1	15.5
Goéland+ δ^+	272	7.0	8.1 %	× 5.3	75.8	14.4
Goéland+ δ^{+}	274	7.1	10.6 %	× 10.3	134.1	39.3
Goéland +DMT	363	6.4	0 %	_	63.4	11.1
Goéland +DMT+δ ⁺	375	6.5	4.5 %	× 3.9	72.1	12.1
Goéland +DMT+ δ^{+}	377	6.5	7.4 %	× 5.2	76.1	12.1

- proofs by Goéland (parallel & concurrent tableaux ATP)
- addition of Deduction Modulo Theory (DMT)
- translated into Coq
- ► size increase, deskolemization time : reasonable

Conclusion¹

What have we seen?

- a strategy to replace Skolem symbols by fresh constants
- in first-order classical logic
- modular in the Skolemization chosen (outer, inner, pre-inner)
- modular in some critical steps (rule replay)
- works in practice (feat. nastily crafted proofs)

What will we do next?

- extension to Deduction Modulo Theory
- extensions of logic (higher-order, dependent types Dedukti)
- generalize wrt to the order nodes linked to a same δ -rule are processed (depth-first, parallel)

¹Thanks to LIRMM, Alma Mater of JR and JC, esp. H. Bouziane, S. Robillard and D. Delahaye.