

Numerical Analysis in Rocq Simplicial Lagrange Finite Elements

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1 Introduction

2 rocq-num-analysis

- State of the Lib
- What is a FE?
- Properties and Lagrange Simplicial FE

3 Difficulties, Conclusion, and Perspectives

Mathematics

$\mathbb{R}, \int, \frac{\partial^2 u}{\partial t^2}$
theorems

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Applied Mathematics

numerical scheme, convergence
algorithms + theorems

Motivations

Mathematics

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theorems

Applied Mathematics

numerical scheme, convergence
algorithms + theorems

Computer Science

floating-point numbers, implementation
programs + ?

Mathematics

$\mathbb{R}, \int, \frac{\partial^2 u}{\partial t^2}$
theorems

Applied Mathematics

time, convergence

Computer Science

floating-point
programs +

representation

Formal Proof

Motivations

PDE (Partial Differential Equations) \Rightarrow weather forecast
 \Rightarrow nuclear simulation
 \Rightarrow optimal control
 \Rightarrow ...

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\Rightarrow real program that implements this scheme or this method

\Rightarrow **towards verifying these programs!**

<http://www.ima.umn.edu/~arnold/disasters/sleipner.html>

The sinking of the Sleipner A offshore platform

Excerpted from a report of [SINTEF](#), Civil and Environmental Engineering:

The Sleipner A platform produces oil and gas in the North Sea and is supported on the seabed at a water depth of 82 m. It is a Condeep type platform with a concrete gravity base structure consisting of 24 cells and with a total base area of 16 000 m². Four cells are elongated to shafts supporting the platform deck. The first concrete base structure for Sleipner A sprang a leak and sank under a controlled ballasting operation during preparation for deck mating in Gandsfjorden outside Stavanger, Norway on 23 August 1991.

Immediately after the accident, the owner of the platform, Statoil, a Norwegian oil company appointed an investigation group, and SINTEF was contracted to be the technical advisor for this group.

The investigation into the accident is described in 16 reports...

The conclusion of the investigation was that the loss was caused by a failure in a cell wall, resulting in a serious crack and a leakage that the pumps were not able to cope with. The wall failed as a result of a combination of a serious error in the finite element analysis and insufficient anchorage of the reinforcement in a critical zone.

A better idea of what was involved can be obtained from this photo and sketch of the platform. The top deck weighs 57,000 tons, and provides accommodation for about 200 people and support for drilling equipment weighing about 40,000 tons. When the first model sank in August 1991, the crash



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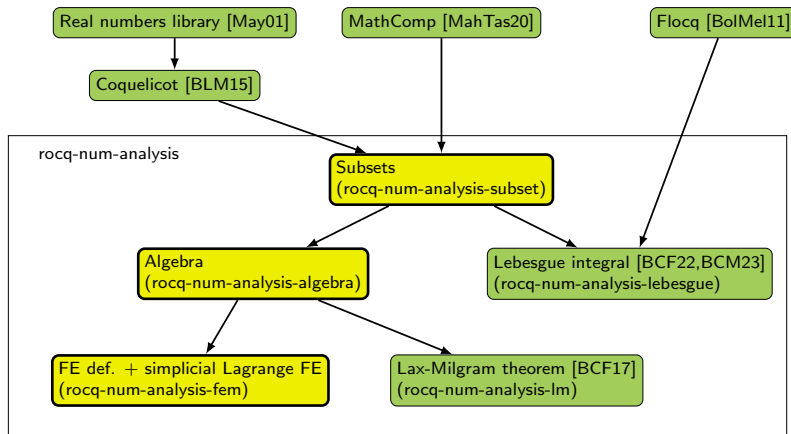
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State of the lib



(155 files, 85 kLoC)

Subsets and Algebra

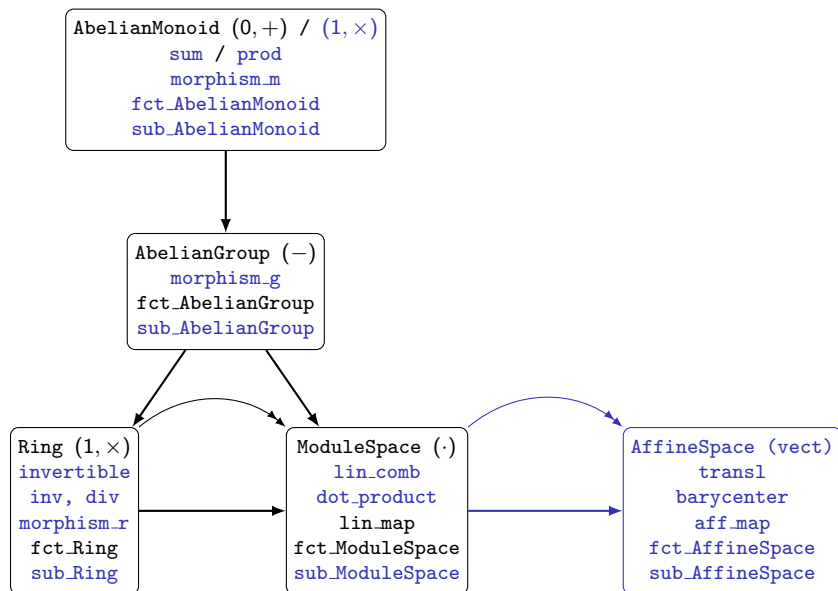
- Subsets

- subsets as $E \rightarrow \text{Prop}$,
- **function restrictions** and their properties.

- Algebra

- finite families (a.k.a vectors),
- linear and affine algebra,
- a **hierarchy** of algebraic structures (see next slide) built upon Coquelicot.

Hierarchy of algebraic structures (incl. Coquelicot in black)



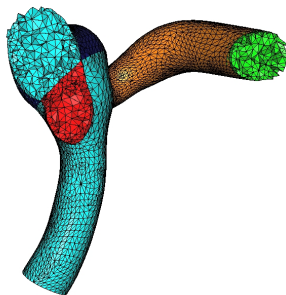
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Mesh



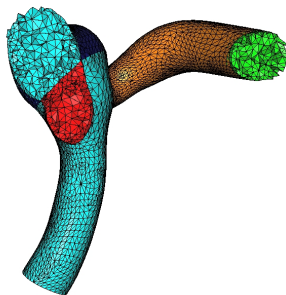
© V. Martin

On a complex geometry, one has a **mesh**, made of triangles / tetrahedrons.

The Finite Element Method aims to approximate the PDE on each element, while constructing a continuous solution.

A **Finite Element** is a geometric element + ???
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© V. Martin

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A **Finite Element** is how to approximate a function (solution of the PDE) by a **simpler function** (eg. polynomial) on a small **simple geometric cell** (eg. tetrahedron), by retaining **particular values** (eg. point values, mean values, fluxes through interfaces) to reduce to a finite-dimension problem.

Definition of a Finite Element

A Finite Element is a triple $(\mathcal{K}, \mathcal{P}, \Sigma)$:

- 1 \mathcal{K} is a **geometric cell**, such as a simplex (segment in \mathbb{R} , triangle in \mathbb{R}^2 , tetrahedron in \mathbb{R}^3)
- 2 \mathcal{P} is a **vector space of functions** on \mathcal{K} , of dimension n_{dof} (often polynomials with bounded degree)
- 3 Σ is composed of n_{dof} **linear forms** on \mathcal{P} .

A Finite Element must have the **unisolvence** property:

For $\Sigma := \{\sigma_i\}_{i \in \{0:n_{dof}-1\}}$, let $\Phi_\Sigma : \mathcal{P} \rightarrow \mathbb{R}^{n_{dof}}$ be

$\Phi_\Sigma(p) := (\sigma_i(p))_{i \in \{0:n_{dof}-1\}}$. Unisolvence means that Φ_Σ is a bijection.

Corresponding Rocq Definition

A FE is either a simplex or a cuboid with the correct number of vertices:

Inductive `shape_type` := `Simplex` | `Cuboid`.

Definition `nvtx_of_shape` (`d` : \mathbb{N}) (`shp` : `shape_type`) : \mathbb{N} :=
 `match` `shp` `with` `Simplex` \Rightarrow `d.+1` | `Cuboid` \Rightarrow 2^d `end`.

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Record FE (d : \mathbb{N}) : Type := mk_FE {
 shape : shape_type;
 nvtx : \mathbb{N} := nvtx_of_shape d shape;
 K_vertices : [0..nvtx] \rightarrow \mathbb{R}^d ;
 K_geom : $\mathbb{R}^d \rightarrow$ Prop := convex_hull K_vertices; (* geometric element K *)
 ndof : \mathbb{N} ;
 P_approx : FRd d \rightarrow Prop; (* approximation space P *)
 P_approx_has_dim : has_dim P_approx ndof;
 S_dof : [0..ndof] \rightarrow FRd d \rightarrow \mathbb{R} ; (* degrees of freedom Σ *)
 S_dof_lm : \forall i, lin_map (S_dof i);
 unisolvence_inj : KerS0 P_approx (gather S_dof);
}.

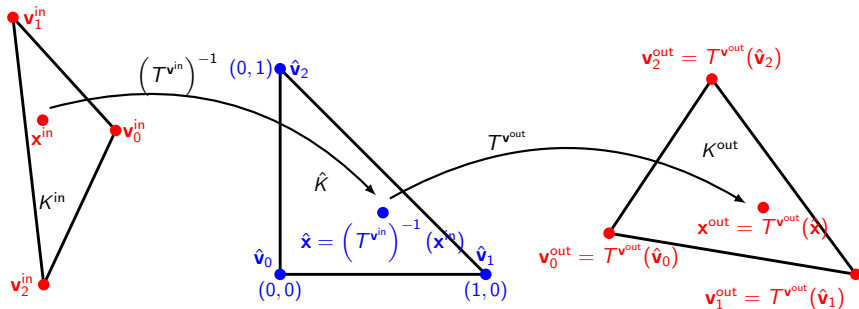
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Geometric Transformation of a Finite Element



From an input finite element and the output vertices \mathbf{v}^{out} , we can **build** an output finite element, relying on the geometric transformation $T_{\mathbf{v}}$ (based on Lagrange polynomials).

Instantiation!

Let us **define** from scratch a FE to check there is no inconsistency.

We **build a d -FE** depending on a variable $k \in \mathbb{N}$. So we need:

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- S_{dof} are the linear forms that take a function and evaluate it at given points for evenly distributed points (called Lagrange nodes), ✓
- a unisolvence proof (Φ_{Σ} is a bijection). ✓

Given d and k , I want the **family of families of \mathbb{N}^d with a sum $\leq k$** .

\hookrightarrow useful in geometry for Lagrange nodes,

\hookrightarrow useful for the monomials on \mathbb{R}^d of degree $\leq k$: $(\mathbf{X}^\alpha)_{\alpha \in \mathcal{A}_d^k}$.

We define \mathcal{A}_d^k (of size $\binom{d+k}{d}$) by concatenation and induction.

Lemma $\text{Adk_sum} : \text{forall } d \ k \ \text{idk}, (\text{sum } (\text{Adk } d \ k \ \text{idk}) \leq k).$

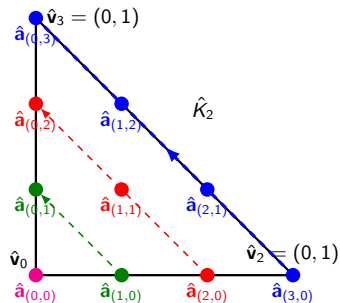
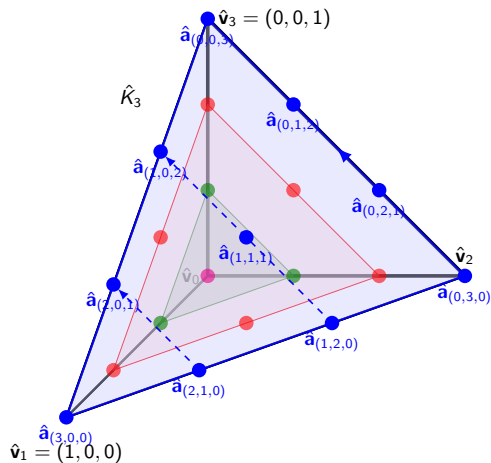
Lemma $\text{Adk_surj} : \text{forall } d \ k \ (b : \mathbb{N}^d), (\text{sum } b \leq k) \rightarrow \{ \text{idk} \mid b = \text{Adk } d \ k \ \text{idk} \}.$

Lemma $\text{Adk_inj} : \text{forall } d \ k, \text{injective } (\text{Adk } d \ k).$

Lemma $\text{Adk_sortedF} : \text{forall } d \ k, \text{sortedF grsymlex_lt } (\text{Adk } d \ k).$

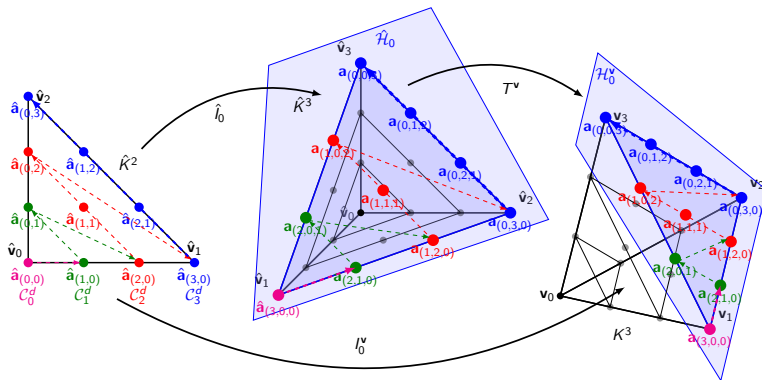
(* a special order near the grevlex order on monomials *)

Reference tetrahedron and triangle with Lagrange nodes



Unisolvence

- long and hard proof,
- begins with a double induction on d and k ,
- needs factorization of polynomials,
- needs injection onto a face hyperplane:



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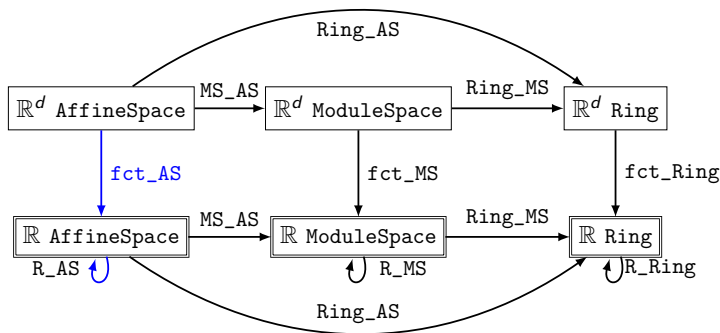
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Difficulties

- chosen proof path: less analysis, and more affine arguments,
- unisolvence proof,
- substructures/restrictions: $E \rightarrow \text{Prop}$ is not a `ModuleSpace`,

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- chosen proof path: less analysis, and more affine arguments,
- unisolvence proof,
- substructures/restrictions: $E \rightarrow \text{Prop}$ is not a ModuleSpace,
- canonical structures. For instance, \mathbb{R}^d is an affine space because:



Conclusion

More details:

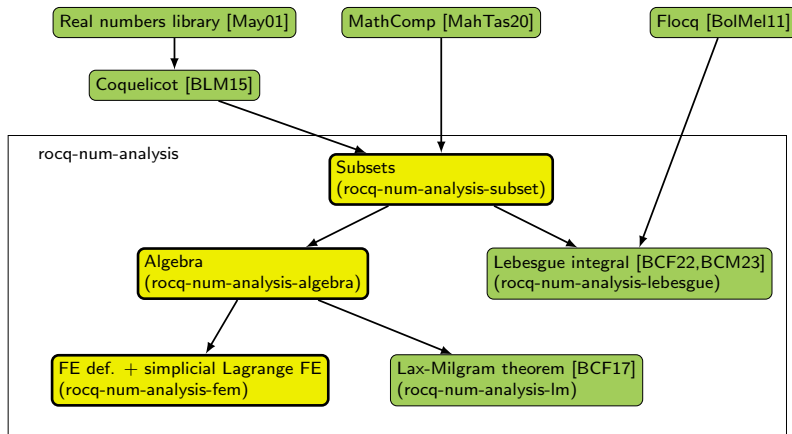
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- **interdisciplinary** work: mathematics / computer science,
- **long-term** work.

Perspectives



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